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Finite element prediction of lasermaterial interaction using COMSOL Multiphysics ®

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Numerical modeling

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Content

> 1. Working with SIMTEC

- 2. Modelling for innovative application
- 3. How to model laser surface texturing?
- 4. Lesson learnt and future work



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Working with SIMTEC

Industry Challenges

- R&D sections: experts in their field
 → Expertise in numerical modelling?
- Lack of time
- FE modelling performed by a small group of people



SIMTEC's Solutions

- Numerical modelling project
 - \rightarrow SIMTEC's member as your colleague
 - ightarrow Help improve your modelling knowledge!
 - \rightarrow Cost-effective outsourcing



MISSI

Numerical modeling

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Our team & Our clients

Numerical Modelling Consultants

6 Members all EngD + PhD

- Extensive research background
- Complex problems
- various fields of expertise

Successful Track Record:

- **Big international compagnies**
- Government laboratories

Involved in Research Consortia

- EU funded projects (REEcover / SHARK)
- PhD projects supervision.







Patrick Namy



Jean-Marc Dedulle



Jean-David Wheeler



Elise Chevallier



Maalek Mohamed-Said





Certified Consultant







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Context

- Surface functionality
 - Friction coefficient
 - Anti-bacterial properties
 - Anti-icing properties
- Texturing processes
 - Surface coating
 - Laser surface texturing
- SHARK project
 - Bring laser surface texturing to industry
 - Advise on the laser parameters selection









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Context

• User

- Specimen, shape, material
- Desired surface function
- Machine: « laser parameters? »

(frequency, pulse duration, average power ...)

- Surface function \rightarrow Topography
- Topography → Laser parameters









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Modelling laser texturing

- Physical phenomena and assumptions
 - Topography prediction
 - \rightarrow Need to understand complex physical mechanisms
 - Multiphysics and multiscale problem
 - M. Dal and R. Fabbro, Optics&LaserTechnology, no. 78, pp. 2-14, 2016.
 - A. Otto and M. Schmidt, *Physics Procedia 5*, pp. 35-46, 2010.



One impact → 2D-axisymmetric geometry

Modelling laser texturing

- Electromagnetic problem
 - Laser source description
 - Laser/matter interaction
- Thermal problem
 - Energy equation

$$\rho C_p \frac{\partial T}{\partial t} + \rho C_p \boldsymbol{u} \cdot \nabla T = \nabla \cdot (k \nabla T) + Q_i$$

- Phase changes: vaporisation and melting
- Fluid Dynamics (CFD)
 - Mass and momentum equations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \boldsymbol{u}) = 0$$
$$\rho \frac{\partial \boldsymbol{u}}{\partial t} + \rho (\boldsymbol{u} \cdot \nabla) \boldsymbol{u} = \nabla \cdot \left[-p \overline{l} + \eta (\nabla \boldsymbol{u} + \nabla \boldsymbol{u}^T) \right] + \boldsymbol{F}_{\boldsymbol{g}}$$

- Recoil pressure
- Surface tension and Marangoni effects



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Modelling laser texturing

• Energy equation

$$\rho C_p \frac{\partial T}{\partial t} + \nabla \cdot (-k\nabla T) = 0$$

- Boundary conditions
 - Thermal heat flux

$$-\boldsymbol{n} \cdot (-k\nabla T) = P_{laser} \cdot \frac{A_0}{\pi \left(\frac{W_0}{2}\right)^2}$$

л

- Numerical convective heat flux $Flux_{vap} = h \cdot (T - T_{vap})$
- Thermal insulation

$$-\boldsymbol{n}\cdot(-k\nabla T)=0$$

• Axial symmetry

Gaussian heat flux $(10^{12}W/m^2)$ 1.2 0.8 0.4 0

Modelling laser texturing

- Phase change modelling
 - Vaporised matter velocity

$$v_{vap} = \frac{Flux_{vap}}{\rho L_v}$$

where L_{v} is the latent heat of vaporization

• Mesh deformation

$$\boldsymbol{v_{mesh}} \cdot \boldsymbol{n} = \boldsymbol{v_{vap}}$$

where $oldsymbol{n}$ is the surface normal vector

• Mass balance not at equilibrium





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Numerical aspects and validation

- Highly non-linear and strongly coupled problem solved with
 - Fine mesh
 - Accurate time-discretization
 - Adapted solver
- Numerical validation (Mass and energy balances)







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Experimental results

- MTC (The Manufacturing Technology Centre)
- Laser parameters
 - Spot ablation (average power, pulse energy)
- Optical metrology equipment
 - 2D/3D profiles

Parameters	Spot ablation
Pulse duration (ns)	200, 100, 50
Beam speed (mm/s)	3000
Frequency (kHz)	30
Power (W)	3, 9, 15, 21, 30



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Comparison of FE predicted and experimental results

- "Peak-to-peak" distance evolution with power
 - Width evolution tendency satisfactory
- Depth evolution with power
 - Improvement required (Recoil pressure law, absorptivity, material properties, vapour interaction influence ...)
- Peak creation
 - Fluid modelling required



×10⁻⁵

Experimental measurements (MTC)
 Finite element predictions (SIMTEC)

-5

Distance away from crater centre (m)

-5

Distance away from crater centre (m)

×10^{-!}

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Application built from the model

• Inputs

- Laser parameters
- Laser path
- Material (database)
- Outcome
 - Temperature field
 - 2D profile of a single impact (width, depth)
 - Plot 3D pattern



Application ran on SIMTEC's servers

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Summary

- Numerical modelling approach of laser material interaction
- Comparison of prediction against experimental measurements
- Topography prediction application to be ran remotely on SIMTEC's servers



Deformation x 20





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Future Work

- More materials for experimental comparison
- Initial surface influence on final topography
 - Surface roughness
- Beyond a single impact
 - Multipass, DLIP, overlap, grove



Sa = 0.25 μm

Sa < 0.15 μm





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Thank you !





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Electromagnetic problem

- Laser source description
 - Thermal heat flux

$$-\boldsymbol{n} \cdot (-k\nabla T) = P_{laser} \cdot \frac{A_0}{\pi \left(\frac{W_0}{2}\right)^2}$$

- Time-dependent
- Interpolation from experimental data
- Laser-matter interaction
 - Absorptivity coefficient



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Thermal Modelling

• Energy equation

$$\rho C_p \frac{\partial T}{\partial t} + \nabla \cdot (-k\nabla T) = 0$$

- Boundary conditions
 - Thermal heat flux

$$-\boldsymbol{n} \cdot (-k\nabla T) = P_{laser} \cdot \frac{A_0}{\pi \left(\frac{W_0}{2}\right)^2}$$

- Numerical convective heat flux $Flux_{vap} = h \cdot (T - T_{vap})$
- Thermal insulation

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Thermal Modelling

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• Mass balance not at equilibrium



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Laser material interaction modelling

- Fluid modelling
 - Navier-Stokes equations

$$\begin{cases} \nabla \cdot \rho \boldsymbol{u} = \boldsymbol{0} \\ \rho(\frac{\partial \boldsymbol{u}}{\partial t} + (\boldsymbol{u} \cdot \nabla)\boldsymbol{u}) = \boldsymbol{\nabla} \cdot \left[-p\overline{\overline{I}} + \eta(\nabla \boldsymbol{u} + \nabla \boldsymbol{u}^T) - \frac{2}{3}\eta(\nabla \cdot \boldsymbol{u})\overline{\overline{I}} \right] + \rho \boldsymbol{g} \end{cases}$$

- Recoil pressure
- Surface tension and Marangoni effects



Deformation x 20